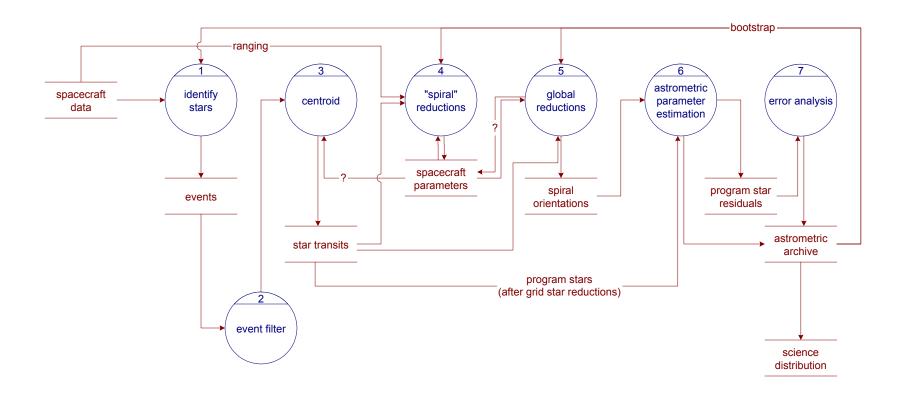
Data Analysis Pipeline Spiral Reduction Prototype Pipe

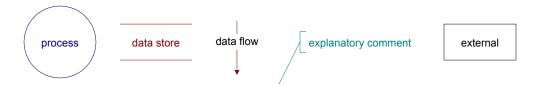
- Where it fits into the pipeline (as now conceived)
- Basis
- Flow chart and organization
- A few details
 - Time variables
 - Changes to NOVAS
- Status
- Next steps

FAME Data Reduction Overview DFD: Astrometric Pipeline

19 March, 2001

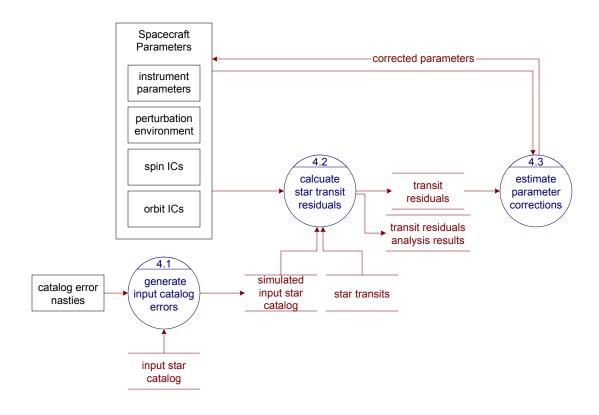


Symbol Key:



FAME Spiral Segment Reduction DFD: Overview

19 March, 2001



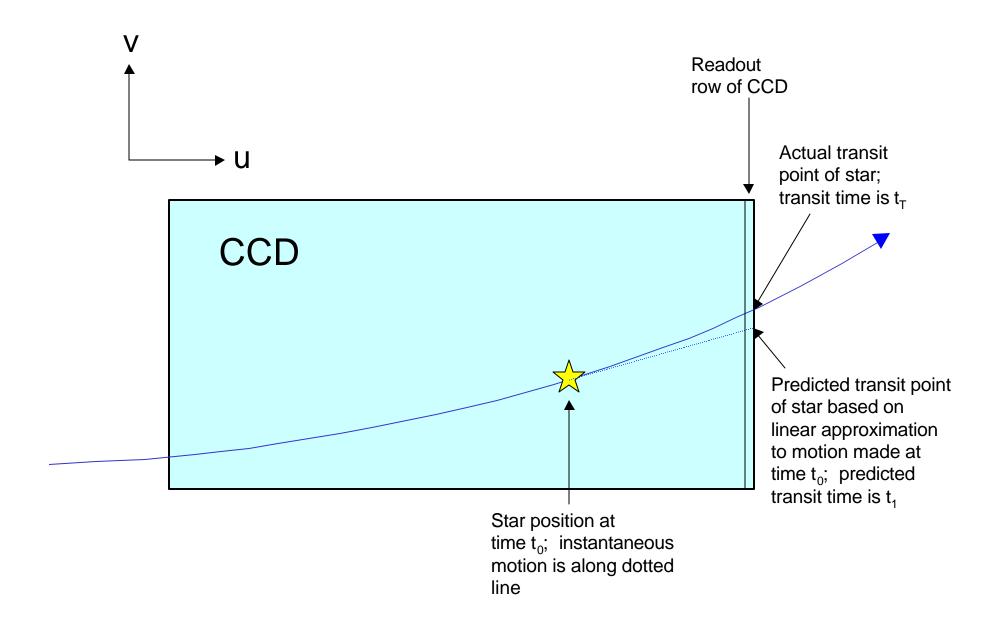
Notes

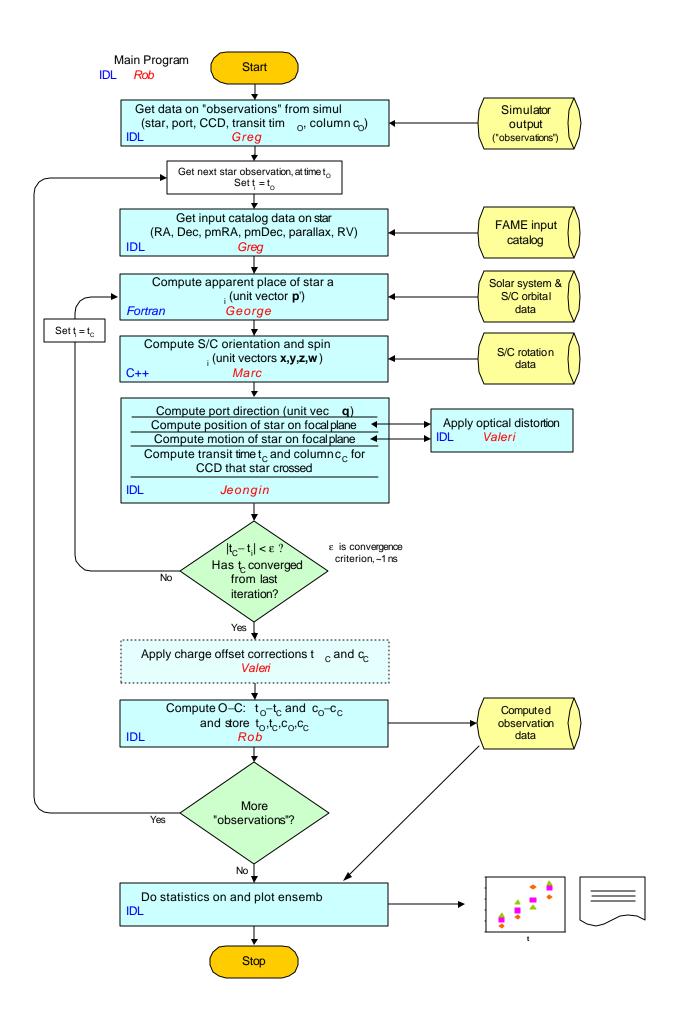
A "transit" consists of two parts: an in-scan precise timing (< $600 \mu as$) and a less-precise (~5-15 mas) cross-scan position.

4.1. It will eventually be not only useful but essential that we introduce various kinds of errors into the input catalog. This allows us to quantify our (in)sensitivity to input catalog systematics.

Basis

- Separate treatment of photons and electrons:
 - First, compute time and column number that the <u>photons</u> of a star image will cross the last row of a CCD.
 - Straightforward geometry, including optical distortion
 - Based on linear approximation to star's path across CCD, applied iteratively if necessary
 - Use of real or simulated observation times as a starting point means that in most cases one iteration should be sufficient
 - Then, compute a correction for the offset of the <u>electron</u> distribution centroid, based on actual (curved) path of star across CCD.
 - Under development
 - Scheme allows for sampling the position of the star on the CCD at as many time points as needed (hopefully only a few will be needed)
- Assumes that computation of the electron-photon difference does not require a numerically evaluated line integral over the star's path for each observations





Time Variables

• Instrument Clock:

Integral seconds
4-byte integer

Fraction of a second 8-byte floating point

• TAI:

Not UTC!

Modified Julian date (including fraction)
8-byte floating point

precision ~1 ì sec synchronization of TAI with instrument clock ~1 msec

NOVAS_FAME (Fortran) Changes to Standard NOVAS

- (1) Subroutines APSTAR, TPSTAR, APPLAN, TPPLAN, ASSTAR, ASPLAN, and MPSTAR removed, since they are specific to Earthbased observations.
- (2) Subroutines VPSTAR, LPSTAR, VPPLAN, and LPPLAN have been modified as follows:
 - (a) A TAI-based MJD is used as the input time argument. (The MJD is sent to GEO_PV directly (see 2d), but converted to a TT-based JD for calls to other NOVAS routines, where the highest time precision is not required.)
 - (b) Input star catalog quantities assumed to be in Hipparcos-like units in the ICRS (J2000.0) coordinate system.
 - (c) The epoch for the star catalog quantities is assumed to be JD 2453737.0 TT (2006.0).
 - (d) The position and velocity of observer—i.e., FAME—is obtained from subroutine GEO_PV, which must be supplied.
 - (e) The input arguments to LPSTAR and LPPLAN have been removed, since they are inappropriate for the FAME case.
 - (f) The output argument from VPSTAR, LPSTAR, VPPLAN, and LPPLAN is a unit vector, not RA and Dec.
 - (g) A return code was added as an output argument.

continued...

NOVAS_FAME changes, continued...

- (3) Various changes made to subroutine VECTRS to be compatible with Hipparcos-like input units. Distance now computed from 1/sin(parallax). Zero-parallax case now set to 10⁻⁹ arcsec.
- (4) Subroutine ANGLES modified to return RA in degrees.
- (5) Subroutine SUNFLD expanded to compute deflection from all nine planets plus the Moon. (Not yet done.)
- (6) Two previous versions of subroutine SOLSYS are included with names changed to SOLS2 and SOLS3. These subroutines are, respectively, SOLSYS version 2 (JPL ephemeris access) and SOLSYS version 3 (self-contained Earth). These are meant to be called from a version of SOLSYS, not supplied here, that can choose among various schemes for obtaining solar system data.

Possible future change:

Complete new relativistic paradigm, which would replace at least ABERAT and SUNFLD, and possibly VECTRS, PROPMO, and GEOCEN as well.

Status

- Portion of pipe to compute O-Cs from simulator data nearly complete
- Testing with simulator data to begin within a few days
- Estimated debugging time: 1 month

Next Steps

- Determine which parameters to initially solve for:
 - ù, ã, clock, CCD alignment errors, etc.
- Develop partials for those parameters; code and test
- Include WLS package into pipe
- Test parameter solutions with simulator data
- Develop and include electron centroid correction